

# Note on the shape circularity measure method based on radial moments

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## Abstract

In this note we show that the, so called, circularity measures based on radial moments, as defined in [1], are a particular case of the circularity measures introduced by [2].

**Keywords:** Shape, Circularity measure, Hu moment invariants, Pattern recognition, Image processing.

## 1 Introduction

A family of circularity measures  $\mathcal{C}_\beta(S)$  was introduced recently in [2]. More precisely, if  $S$  denotes a planar shape,  $\mu_{0,0}(S)$  is the area of  $S$ , and  $\beta$  is a number from the interval  $(-1, \infty)$ , then the quantities  $\mathcal{C}_\beta(S)$  indicate/measure how much the considered shape  $S$  differs from a planar circular disc, of the same area as the given shape  $S$ . The formal definition, of the circularity measures  $\mathcal{C}_\beta(S)$ , is as follows.

**Definition 1** *Let  $S$  be a given shape whose centroid coincides with the origin and a real  $\beta$  such that  $-1 < \beta$  and  $\beta \neq 0$ . Then the circularity measure  $\mathcal{C}_\beta(S)$  is defined as*

$$\mathcal{C}_\beta(S) = \begin{cases} \frac{\mu_{0,0}(S)^{\beta+1}}{(\beta+1)\pi^\beta \iint_S (x^2+y^2)^\beta dx dy}, & \beta > 0 \\ \frac{(\beta+1)\pi^\beta \iint_S (x^2+y^2)^\beta dx dy}{\mu_{0,0}(S)^{\beta+1}}, & \beta \in (-1, 0). \end{cases} \quad (1)$$

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The formula in (1) is given in Cartesian coordinates. If the polar coordinate system is involved (instead of the Cartesian coordinate system):

$$x = r \cdot \cos\theta, \quad y = r \cdot \sin\theta \quad (\text{the Jacobian for this coordinate transformation is } |J| = r)$$

then

$$\iint_S (x^2 + y^2)^\beta dx dy = \int_\theta \int_r ((r \cdot \cos\theta)^2 + (r \cdot \sin\theta)^2)^\beta \cdot r dr d\theta = \int_\theta \int_r r^{2\beta+1} dr d\theta$$

and consequently (1) becomes

$$\mathcal{C}_\beta(S) = \begin{cases} \frac{\mu_{0,0}(S)^{\beta+1}}{(\beta+1)\pi^\beta \int_\theta \int_r r^{2\beta+1} dr d\theta}, & \beta > 0 \\ \frac{(\beta+1)\pi^\beta \int_\theta \int_r r^{2\beta+1} dr d\theta}{\mu_{0,0}(S)^{\beta+1}}, & \beta \in (-1, 0). \end{cases} \quad (2)$$

Now, by setting  $\beta = \frac{p}{2}$ , the first expression (for  $\beta > 0$ ) in (2) becomes

$$\mathcal{C}_\beta(S) = \mathcal{C}_{p/2}(S) = \frac{\frac{2}{p+2} \cdot \pi^{-p/2} \cdot \mu_{0,0}(S)^{\frac{p+2}{2}}}{\int_\theta \int_r r^{p+1} dr d\theta}. \quad (3)$$

Circularity measures based on radial moments, introduced in [1], are denoted by  $\zeta_p(D)$  and formally defined, by the expression in (9) from [1], as

$$\zeta_p(D) = \frac{\frac{2}{p+2} \cdot \pi^{-p/2} \cdot [u_0(D)]^{\frac{p+2}{2}}}{u_p(D)}. \quad (4)$$

Further, [1] uses the following denotation

- $u_p(D) = \iint_D (r - \bar{r})^p ds$ , with  $ds = r \cdot dr \cdot d\theta$   $\bar{r} = \sqrt{x_c^2 + y_c^2}$ , and

$$(x_c, y_c) = \left( \frac{\iint_D x ds}{\iint_D ds}, \frac{\iint_D y ds}{\iint_D ds} \right) \quad \text{being the centroid of the considered shape } D.$$

(Notice:  $u_0(D) = \mu_{0,0}(D)$  and  $u_p(D) = \int_\theta \int_r r^{p+1} dr d\theta$ , if  $\bar{r} = 0$ , i.e.  $(x_c, y_c) = (0, 0)$ .)

Finally, since  $\zeta_p(D)$  is translation invariant (see Theorem 2 from [1]) we can set  $\bar{r} = 0$  (i.e. we can assume that the shape  $D$  is translated such that its gravity center  $(x_c, y_c)$  coincides with the origin  $(0, 0)$ ), and deduce that (for  $p > 0$ )

$$\zeta_p(D) = \mathcal{C}_{p/2}(D). \quad (5)$$

In other words, the formula in (4) is equivalent to the formula in (3), and further, shape circularity measures  $\zeta_p(D)$  based on radial moments, from [1], are particular subcases of the family of circularity measures  $\mathcal{C}_\beta(S)$ , introduced by [2] (measures from [2] are defined for  $\beta = \frac{p}{2}$  negative, as well).

It is worth mentioning that the identity in (5) is evident in the experimental results from Table 1 in [1], which includes  $\mathcal{C}_p(D)$  denoted by  $H_p(D)$ . Although there is a systematic offset between  $\zeta_p(D)$  and  $\mathcal{C}_{p/2}(D)$ , possibly caused by digitization and numerical errors, the results for  $\zeta_{p=2}(D)$  are similar to  $\mathcal{C}_{p=1}(D)$ , such that their ratios are all the same to within 3 significant places. Likewise, the ratios of  $\zeta_{p=4}(D)$  and  $\mathcal{C}_{p=2}(D)$  are the same to within 3 significant places.

## References

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