

1 Detecting the Geospatialness of Prepositions from 2 Natural Language Text

3 **Mansi Radke** 

4 Computer Science and Engineering Department, Visvesvaraya National Institute of Technology,
5 Nagpur, India
6 mansiaradke@gmail.com

7 **Prarthana Das**

8 Computer Science and Engineering Department, Visvesvaraya National Institute of Technology,
9 Nagpur, India
10 musiciselixir@gmail.com

11 **Kristin Stock** 

12 Massey Geoinformatics Collaboratory, Massey University, Auckland, New Zealand
13 k.stock@massey.ac.nz

14 **Christopher B. Jones** 

15 School of Computer Science and Informatics, Cardiff University, Cardiff, United Kingdom
16 jonescb2@cardiff.ac.uk

17 — Abstract —

18 There is increasing interest in detecting the presence of geospatial locative expressions that include
19 spatial relation terms such as *near* or *within <some distance>*. Being able to do so provides a
20 foundation for interpreting relative descriptions of location and for building corpora that facilitate
21 the development of methods for spatial relation extraction and interpretation. Here we evaluate the
22 use of a spatial role labelling procedure to distinguish geospatial uses of prepositions from other
23 spatial and non-spatial uses and experiment with the use of additional machine learning features
24 to improve the quality of detection of geospatial prepositions. An annotated corpus of nearly 2000
25 instances of preposition usage was created for training and testing the classifiers.

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31 **1** Introduction

32 Automated recognition and disambiguation of geographic references in text documents has
33 received considerable attention in recent years, often with the motivation of indexing the
34 documents with regard to geographic space. The methods used to date have been dominated
35 by a focus on identifying geographic names, i.e. toponyms, and using these directly as the
36 basis for geographic footprints for text expressions or entire documents. The assumption
37 however is that the references are absolute in the sense that the toponym provides the actual
38 location referred to. While this is a reasonable default assumption, it is very common to
39 refer to locations in an indirect manner using spatial relations, such as *near*, *at*, *close to*,
40 *north of* etc., relative to a reference location. These expressions often take the form of triples
41 of a subject (or located object), the spatial relation and an object (the reference location),
42 as in “St Mary Church near Times Square.” While some authors have proposed methods
43 for modelling vague spatial relations such as *near* (e.g. [7, 10, 11]), relatively little work
44 has been done on the basic, initial problem of reliably identifying the presence of relative



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45 locational descriptions in natural language texts ([3, 5, 6, 8]). Effective methods for doing
46 this are required as part of the process of extracting and interpreting indirect geographic
47 references and to retrieve other geospatial facts that associate an event or some other object
48 with a reference location, as for example in “Roald Dahl was born in Cardiff”. Locational
49 description detection methods are also required for automatic creation of test collections
50 that can be used in developing and evaluating methods for spatial relation extraction and for
51 modelling the use of individual spatial relations, e.g. [9]. In this paper, we present methods
52 for automatic detection of spatial relational terms in sentences, in particular prepositions,
53 that are used specifically in a geospatial sense and we distinguish these from prepositions
54 that have other spatial senses and from prepositions that have no spatial meaning. We are
55 interested in the ability to distinguish between spatial and geospatial senses of prepositions,
56 as this is important for detecting text that can be georeferenced and thus mapped on a
57 geographical scale (in contrast to text that describes a location inside a room, or on a person’s
58 body), a goal that is useful in a wide range of application areas.

59 The approach adopted here applies the spatial role labelling method of [3]. That work
60 aimed to detect all three components of spatial relational expressions which were referred to
61 as the trajector, i.e. the located object, spatial indicator, i.e. the individual preposition that
62 serves as spatial relation, and the landmark which is the reference location. Here we use
63 their preposition disambiguation method, which was employed as part of a pipeline approach
64 to detection of triples. The method was tested in [3] only for the purpose of detecting generic
65 spatial prepositions, which might or might not be geospatial. Here we train the classifier on
66 sentences containing a preposition that is used either in a geospatial sense, a spatial but not
67 geospatial sense, or in a sense that is not spatial in any respect. We also experiment with
68 modifying the classifier for geospatial prepositions to take account of other evidence that
69 indicates the presence of place names and geographic feature types.

70 For the purpose of evaluating the approach, we have created a corpus of 1876 instances of
71 preposition usage that have been manually labelled as geospatial, spatial (but not geospatial)
72 and non-spatial. These prepositions occur within 674 sentences.

73 In the remainder of the paper Section 2 describes related work, Section 3 explains
74 the methodology in detail, while Section 4 gives the details of the data set used and the
75 experiments performed. Section 5 concludes the paper, pointing out some directions for
76 future work.

77 **2** Related work

78 A method specifically designed to detect whether a preposition has a spatial sense was
79 presented by Kordjamshidi et al. [3] in a paper on spatial role labelling in the context of
80 relation extraction. The paper focused on the three roles of trajector (located object), spatial
81 indicator (spatial relation) and landmark (reference location). Two approaches to spatial
82 role labelling were presented. In the first approach, called the pipeline approach, an input
83 sentence is passed to the first stage of the pipeline which tokenizes the sentence and passes
84 each token to a Part of Speech (POS) tagger. The sentence is also processed by a dependency
85 parser and a semantic role labeller (the [LTH software](#) from [1]). If a preposition is identified
86 by the POS tagger, a Naive Bayes classifier is used to make a decision on whether it is used in
87 a spatial sense. The features used by the classifier are based on output from the POS tagger,
88 the dependency parser and the semantic role labeller. For this stage of identifying the spatial
89 sense of a preposition, an F1 score of .88 was achieved for the TPP dataset [4] with 10 fold
90 cross validation. If the preposition is determined to have a spatial sense, then it is passed to

91 a second stage of the pipeline which identifies the trajector and the landmark with respect to
92 the spatial indicator. This second stage uses probabilistic graphical models, in particular a
93 Conditional Random Fields classifier, which again takes a variety of features generated by the
94 initial parsing of the sentence. A triple of the form $\langle \text{Trajector}, \text{SpatialIndicator}, \text{Landmark} \rangle$
95 is returned as output by the pipeline. The second approach offered by Kordjamshidi et al.
96 [3] uses joint learning in which all three of trajector, spatial indicator and landmark are
97 detected simultaneously.

98 A method for detecting just the spatial relation and the reference object of spatial relations
99 was described by Liu [5] where these partial relations were described as degenerate locative
100 expressions (DLE). The approach is analogous to methods of Kordjamshidi et al., though
101 they employed a smaller set of features for machine learning, that did not include dependency
102 relations or semantic roles. An evaluation of the method in [6] obtained an F1 score of .76
103 when applied fully automatically to their TellUsWhere corpus on which it was trained. Note
104 that no distinction was made in that work between geospatial and other spatial senses of
105 prepositions. The method of [5] to extract DLEs was also exploited in Khan et al. [2] in
106 which locative DLEs which explicitly encode spatial relations, with prepositions such as *near*
107 and *in*, were distinguished from partial DLEs where a preposition such as *to* was not regarded
108 as conveying explicit spatial information. A rule based approach was employed to extend the
109 latter to an explicit spatial DLE when it was used as part of a spatial relation such as *next*
110 *to*. This technique was part of a procedure to extract spatial triples by matching structures
111 from the Stanford parser, of the form $\langle \text{governor}, \text{preposition}, \text{dependent} \rangle$, with locative
112 DLEs that used the same preposition. The governor would then serve as the located object
113 of a spatial triple.

114 As part of a process of creating a corpus of geospatial sentences, Stock et al. [8] employed
115 a set of language patterns to detect various ways in which geospatial information is described.
116 This included a pattern to recognise when a place name or place type is preceded by a spatial
117 relation which could be a preposition (though other parts of speech were also considered to
118 represent spatial relations). They obtained a precision of 0.66 when applying these methods
119 to detect geospatial expressions. A specialized collection of spatial relational expressions was
120 created by Wallgrun, Klippel and Baldwin [9]. They used search patterns to query the web
121 to find expressions that contained any of the three relations of *near*, *close* and *next to*. Their
122 approach therefore constrained the results to include the specified spatial relation. They
123 also confined the expressions to include specified types of located and reference objects. Our
124 work differs from that in allowing any spatial relation that is classed as a preposition and in
125 using a machine learning approach to determine the geospatial or other spatial sense of the
126 preposition.

127 **3** Methods

128 **3.1** What is a geospatial sense?

129 In order to distinguish here between geospatial, other spatial and non-spatial uses of preposi-
130 tions, we employ a simple definition of a geospatial relation as one in which the preposition
131 has a spatial sense and the reference object to which the preposition applies is a geographic
132 feature, as in a named place or a geographic feature type. The reference object is normally
133 expected to be outdoors. If it is part of a building it is expected to be an exterior part. We
134 impose no constraint on the nature of the located object. If a preposition has a spatial sense
135 but the reference object is not geographic then it is classed as spatial. If the preposition has
136 no spatial interpretation then it is classed as neither geospatial nor spatial.

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137 Examples of the kinds of expressions that appear on our corpus include the following,
138 with preposition senses according to our annotation scheme (described above) shown in
139 angular brackets:

140 ■ “And now on <non-spatial> a clear morning Graham Little and I are sitting at <geospa-
141 tial> the bottom of (spatial) the wall fit and ready to go and the wall is plastered with
142 <non-spatial> verglas.”

143 ■ “In <non-spatial> a minute she had rushed from <geospatial> the house and was running
144 down <geospatial> the garden”

145 3.2 Classifying prepositions as geospatial or spatial

146 In this work, we modify the first step of the spatial role labelling pipeline method of [3], i.e.
147 their method for detecting the spatial sense of prepositions, by adding additional features
148 for machine learning. The features used in the original classifier are listed in Table 1. As
149 indicated above these are obtained from a combination of a POS tagger, a dependency
150 parser and a semantic role labeller. The Part-Of-Speech Tagger (POS Tagger) assigns parts
151 of speech to each word, such as noun, verb, adjective, etc. Dependency parsing assigns a
152 syntactic structure to a sentence. The most widely used type of syntactic structure is a
153 parse tree which can be useful in various applications such as grammar checking, but here it
154 plays a critical role in the semantic analysis stage. In natural language processing, semantic
155 role labeling (also called shallow semantic parsing) is a process that assigns labels to words
156 or phrases in a sentence to indicate their semantic role, such as that of an agent, goal, or
157 result. It consists of the detection of the semantic arguments associated with the predicate
158 or verb of a sentence and their classification into their specific roles. We experiment with
159 using just these features, but we also extend the method to add additional features that
160 indicate whether a place name or a geographic place type is present in the expression that
161 includes the target preposition. The presence of a place name is detected with the Geonames
162 gazetteer, while the presence of a place type is detected with a dictionary of geographic
163 place types. The `expat` application was used to generate these features (location and gnn
164 patterns).

165 We used a Naive Bayes multi-class classifier with three output classes of geospatial, spatial
166 but not geospatial, and neither geospatial nor spatial. We also used Naive Bayes binary
167 classifiers for each one of these three classes *vs* the other two classes.

168 4 Experimental Set Up

169 4.1 Data set and its Annotation

170 Our dataset of 674 sentences was derived from two sources. 185 of the sentences came
171 from the source of about 26,000 sentences that were used in the process of creating the
172 Nottingham Corpus of Geospatial Language (NCGL) [8]. These sentences were harvested
173 from the web using the algorithm described in [8], and was thus biased towards retrieving
174 geospatial content, but also included spatial (but non-geospatial) expressions as well as some
175 uses of prepositions that are non-spatial in any sense. The remainder of our collection is a
176 sample of the TPP dataset of sentences produced for the preposition project (see Litkowski
177 and Hargraves [4]). That dataset includes many examples of both spatial and non-spatial
178 uses of prepositions, though relatively few of them have a geographical context.

179 Many of the sentences include multiple prepositions and so in order to annotate the sense
180 of the individual prepositions we created a distinct instance of a sentence for each preposition

preposition	the preposition itself
preposition	the lemma of the preposition
preposition	the POS tag of the preposition
preposition	the DPRL of the preposition
preposition	the semantic role label of the preposition
preposition	the sense of the preposition if assigned
preposition	the argument of the preposition in the SRL output
head1	the head1 itself
head1	the lemma of head1
head1	the POS tag of the head1
head1	the DPRL of the head1
head1	the semantic role label of the head1
head1	the sence of the head1 if assigned
head1	the argument of the head1 in the SRL output
head2	the head2 itself
head2	the lemma of head2
head2	the POS tag of the head2
head2	the DPRL of the head2
head2	the semantic role label of the head2
head2	the sence of the head2 if assigned
head2	the argument of the head2 in the SRL output

■ **Table 1** Features from [3] used in detecting the sense of a preposition

181 that it contained (as determined by a POS tagger). We considered a tuple $\langle \text{Sentence},$
 182 $\text{Preposition} \rangle$ as a unique instance. So, if a sentence instance s had two prepositions $p1$ and
 183 $p2$, we created two instances from it, namely $\langle S, p1 \rangle$ and $\langle S, p2 \rangle$. This resulted in
 184 1876 instances (indicating an average of just under three prepositions per sentence). These
 185 preposition-specific instances were then manually annotated as either geospatial, spatial (but
 186 not geospatial) or non-spatial.

187 Annotation was conducted through an iterative process that involved all four authors. In
 188 the case of the NCGL sentences, one person annotated all sentences, a subset of 100 of which
 189 were then checked by two others followed by a discussion of disagreements. A fourth person
 190 then re-annotated all of those sentences taking account of issues raised in the discussions.
 191 The TPP sentences were annotated by one person, after which one other checked them and
 192 highlighted disagreements. The first annotator then revised annotations to respect the result
 193 of this discussion. Finally a further stage of re-annotation of subsets of 100 of each of both
 194 groups of sentences was performed resulting in inter-annotator agreements of 0.89 for the
 195 larger TPP sourced data set and 0.75 for the NCGL sourced data set.

196 As an example of inter-annotator disagreement, consider the following sentence. “After
 197 50m, you will reach a road with wide verges where you turn left toward Lambley.” The first
 198 annotator marked *after* as non-spatial in sense. The second annotator noted that here *after*
 199 is used to represent the geospatial arrangement of different locations, and the latter sense
 200 was adopted for the final data set. In another example, in the phrase “Republic of China”,
 201 the preposition *of* was marked spatial by one annotator, as “China” is a geographical place
 202 name, while the other annotator considered it as non spatial since “Republic of China” is an
 203 administrative entity. We adopted this latter annotation for the final data set.

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204 4.2 Experiments performed

205 Before we present our results, we mention the balance of the classes in the dataset used.
 206 Out of the total preposition instances (1877), the number of instances marked as non-spatial
 207 was 770, the number of instances marked as spatial was 773, and the number of instances
 208 marked as geospatial was 334.

■ **Table 2** Features used in experiments

Kord	All features used for preposition sense detection in [3]
Kord-Geo	The features from Kord plus the number of placenames and the number of geographic feature types found in the head words of the preposition
Kord-Geo-S	The features from Kord plus the number of place names and the number of geographic feature types found within the entire sentence in which the preposition occurs
Kord-Geo-All	The features from Kord-Geo-S plus the sum of the numbers of place names and a binary value of true if either a place name or a geographic feature type is present
Geo-Baseline-S	The number of place names and the number of geographic feature types found within the entire sentence in which the preposition occurs

■ **Table 3** Results for 3-class classifier predicting geospatial, spatial (but not geospatial) or neither

	Geospatial			Spatial			Neither		
	Prec	Rec	F1	Prec	Rec	F1	Prec	Rec	F1
Kord	0.442	0.578	0.501	0.747	0.744	0.745	0.763	0.664	0.710
Kord-Geo	0.514	0.614	0.559	0.751	0.762	0.757	0.772	0.696	0.732
Kord-Geo-S	0.566	0.638	0.600	0.732	0.802	0.765	0.783	0.665	0.719
Kord-Geo-All	0.600	0.692	0.643	0.749	0.797	0.772	0.796	0.692	0.740

■ **Table 4** Results for three 2-class classifiers predicting geospatial, spatial (but not geospatial) and neither

	Geospatial			Spatial			Neither			Spatial or Geospatial		
	Prec	Rec	F1	Prec	Rec	F1	Prec	Rec	F1	Prec	Rec	F1
Kord	0.370	0.647	0.471	0.696	0.790	0.740	0.762	0.751	0.756	0.828	0.836	0.832
Kord-Geo	0.423	0.680	0.521	0.704	0.798	0.748	0.760	0.755	0.757	0.830	0.835	0.832
Kord-Geo-S	0.480	0.704	0.570	0.688	0.846	0.759	0.755	0.753	0.754	0.829	0.830	0.829
Kord-Geo-All	0.542	0.728	0.621	0.672	0.837	0.745	0.750	0.771	0.761	0.838	0.821	0.829
Geo-Baseline-S	0.625	0.419	0.502	0.494	0.889	0.635	0.422	0.326	0.368	0.595	0.689	0.639

209 Several experiments were conducted with a Naive Bayes classifier to evaluate the methods
 210 described above (note that the original method from [3] uses this classifier for determining
 211 the sense of a preposition). In the first experiment (Table 3) a multi-class Naive Bayes
 212 classifier was used to predict each of the three classes of geospatial, spatial (but not geospatial)
 213 and neither. There were several versions of the classifier that use different combinations
 214 of features (summarised in Table 2). One of these (Kord) just uses the features from [3]
 215 described above. It resulted in an F1 value of 0.50 for the geospatial class and better values
 216 of 0.745 for spatial and 0.710 for neither. This was extended by adding the two features of
 217 the number of place names and number of geographical features detected in the head words
 218 of the preposition that is being tested (Kord-Geo). Note that the head words are among
 219 the features generated by the procedure used in [3]. They correspond to the subject and
 220 object of the preposition. A further variation (Kord-GeoS) records these latter numbers at
 221 the sentence level, which was found to improve upon the performance when only observing
 222 head words (though note that the quality of performance will depend upon the performance

223 of the script to detect place names and geo-feature types). Experiments to employ features
224 consisting of a binary value to record whether a place name or geo-feature were present and,
225 separately, of a value that is the sum of the numbers of place names and geo-feature types,
226 did not improve on sentence level performance and are not listed here. However, combining
227 these latter data items with those in Kord-Geo-S did provide an improvement (referred to as
228 feature set Kord-Geo-All) with an F1 for Geospatial of 0.643.

229 In addition to the three class classifiers we implemented several 2-class classifiers (see
230 Table (4) with target classes of geospatial (*vs* spatial or neither), spatial *vs* (geospatial or
231 neither) and neither (*vs* geospatial or spatial). Just as with the 3-class classifiers we used
232 either just Kordjamshidi features (Kord), and place name and geographic features from the
233 preposition's head words (Kord-Geo) and from the whole sentence in which the preposition
234 occurred (Kord-GeoS). We also tested the method using Kord-Geo-All features, which gave
235 the best 2-class performance for geospatial sense with an F1 of 0.621 but this did not improve
236 on the result from the 3-class classifier. Output from the 2-class classifiers also included
237 the complement of the Neither class, i.e. detection of prepositions that are either used in a
238 spatial or a geospatial sense, which is equivalent to preposition classification task in [3]. We
239 obtained an F1 value of 0.832 when using just the original features from [3].

240 As a baseline (Geo-Baseline-S) we implemented a Naive Bayes method for detecting
241 whether a preposition has a geospatial sense, that uses, as machine learning features, just the
242 presence of a place name and the presence of a geographic feature type. This was conducted
243 at the preposition specific level, in which their presence was recorded only in the head words
244 of the preposition, and at the level of whether they occurred anywhere in the sentence. The
245 latter approach gave the better performance with an F1 of 0.502.

246 **5** Conclusions and future directions

247 In this paper we have experimented with a method for detecting the geospatial nature of
248 prepositions in sentences using a machine learning approach that was developed in [3] for
249 generic spatial role labelling. Using a corpus of sentences annotated as either geospatial,
250 spatial (but not geospatial) or neither geospatial nor spatial, we found that, when trained
251 on this corpus, the original method was not able to detect geospatial prepositions with
252 an F1 value greater than 0.50. However, it detected the spatial (but not geospatial) class
253 with F1 of .745 and it detected prepositions that are used with either a geospatial or a
254 spatial sense with an F1 of 0.832. We have adapted the method in an effort to improve its
255 performance for detecting geospatial sense by adding features (for machine learning) that
256 record whether a place name or a geospatial feature type is present in the head words that
257 serve as subject and object of the preposition or, alternatively, whether they are present
258 in the entire sentence. Using the sentence level features provided better performance with
259 an F1 of 0.643 for geospatial sense. It also resulted in an improvement in detection of the
260 spatial (but not geospatial) class with an F1 of 0.772. It may be noted that a classifier using
261 only the presence of a place name or geographic feature type in the sentence provided better
262 performance than the basic spatial role labelling method.

263 In future work we will investigate methods to make further improvements to the perform-
264 ance of the methods presented here. In particular we will address a limitation of the current
265 method with regard to detection of place names and feature types by using a richer gazetteer
266 and extending the dictionary of geographical feature types.

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